ESP32-SOLO-1 Datasheet



Espressif Systems

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About This Guide

This document provides the specifications for the ESP32-SOLO-1 module.

Release Notes

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2017.11	V1.0	First release.

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1. Overview

ESP32-SOLO-1 is a powerful, generic Wi-Fi+BT+BLE MCU module that targets a wide variety of applications, ranging from low-power sensor networks to the most demanding tasks, such as voice encoding, music streaming and MP3 decoding.

At the core of this module is the ESP32-SOWD chip. ESP32-SOWD is a member of the ESP32 family of chips, yet it features a single core and packs all the peripherals of its dual-core counterpart. Available in a 5x5 mm QFN, it offers great value for money, with its flawless performance when powering complex IoT applications. For details on the part number of the ESP32 series, please refer to Chapter **Part Number and Ordering Information**, in <u>ESP32</u> <u>Datasheet</u>.

The integration of Bluetooth, Bluetooth LE and Wi-Fi ensures that a wide range of applications can be targeted, and that the module is future proof: using Wi-Fi allows a large physical range and direct connection to the internet through a Wi-Fi router, while using Bluetooth allows the user to conveniently connect to the phone or broadcast low energy beacons for its detection. The sleep current of the ESP32 chip is less than 5 μ A, making it suitable for battery powered and wearable electronics applications. ESP32 supports a data rate of up to 150 Mbps, and 20.5 dBm output power at the antenna to ensure the widest physical range. As such the chip does offer industry-leading specifications and the best performance for electronic integration, range, power consumption, and connectivity.

The operating system chosen for ESP32 is freeRTOS with LwIP; TLS 1.2 with hardware acceleration is built in as well. Secure (encrypted) over the air (OTA) upgrade is also supported, so that developers can continually upgrade their products even after their release.

Table 2 provides the specifications of ESP32-SOLO-1.

Categories	Items Specifications			
		802.11 b/g/n/e/i (802.11n up to 150 Mbps)		
	Protocols	A-MPDU and A-MSDU aggregation and 0.4 μ s guard		
Wi-Fi		interval support		
	Frequency range	2.4 ~ 2.5 GHz		
	Protocols	Bluetooth v4.2 BR/EDR and BLE specification		
		NZIF receiver with -97 dBm sensitivity		
Bluetooth	Radio	Class-1, class-2 and class-3 transmitter		
		AFH		
	Audio	CVSD and SBC		
		SD card, UART, SPI, SDIO, I2C, LED PWM, Motor		
	Module interface	PWM, I2S, IR		
		GPIO, capacitive touch sensor, ADC, DAC, LNA pre-		
		amplifier		
	On-chip sensor	Hall sensor, temperature sensor		
	On-board clock	40 MHz crystal		
Hardware	Operating voltage/Power supply	2.7 ~ 3.6V		
	Operating current	Average: 80 mA		

Categories	Items	Specifications		
	Minimum current delivered by	500 mA		
	power supply			
	Operating temperature range	-40°C ~ +85°C		
	Ambient temperature range	Normal temperature		
	Package size	18±0.2 mm x 25.5±0.2 mm x 3.1±0.15 mm		
	Wi-Fi mode	Station/SoftAP/SoftAP+Station/P2P		
	Wi-Fi Security	WPA/WPA2/WPA2-Enterprise/WPS		
	Encryption	AES/RSA/ECC/SHA		
	Firmware upgrade	UART Download / OTA (download and write firmware		
Software		via network or host)		
	Software development	Supports Cloud Server Development / SDK for cus-		
		tom firmware development		
	Network protocols	IPv4, IPv6, SSL, TCP/UDP/HTTP/FTP/MQTT		
	User configuration	AT instruction set, cloud server, Android/iOS app		

2. Pin Definitions

2.1 Pin Layout

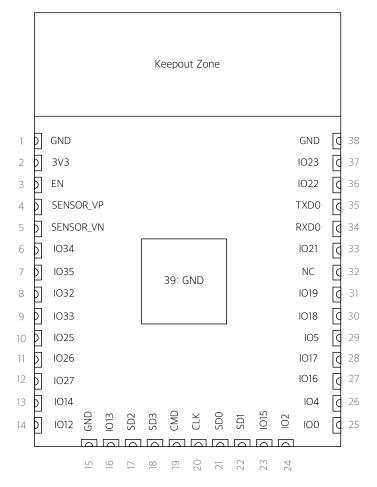


Figure 1: ESP32-SOLO-1 Pin layout

2.2 Pin Description

ESP32-SOLO-1 has 38 pins. See pin definitions in Table 3.

Name	No.	Туре	Function	
GND	1	Р	Ground	
3V3	2	Р	Power supply.	
EN	3	I	Chip-enable signal. Active high.	
SENSOR_VP	4	I	GPIO36, SENSOR_VP, ADC_H, ADC1_CH0, RTC_GPIO0	
SENSOR_VN	5	1	GPIO39, SENSOR_VN, ADC1_CH3, ADC_H, RTC_GPIO3	
IO34	6	I	GPIO34, ADC1_CH6, RTC_GPIO4	
IO35	7	1	GPIO35, ADC1_CH7, RTC_GPIO5	
1032	8	3 I/O	GPIO32, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4,	
	0		TOUCH9, RTC_GPIO9	

Table 3: Pin Definitions

Name	No.	Туре	Function	
IO33	9	I/O	GPIO33, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5, TOUCH8, RTC_GPIO8	
1025	10	I/O	GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0	
1026	11	1/O	GPI026, DAC_2, ADC2_CH9, RTC_GPI07, EMAC_RXD1	
1027	12	1/O	GPI027, ADC2_CH7, TOUCH7, RTC_GPI017, EMAC_RX_DV	
1021			GPI014, ADC2_CH6, TOUCH6, RTC_GPI016, MTMS, HSPICLK,	
IO14	13	I/O	HS2_CLK, SD_CLK, EMAC_TXD2	
	- 4		GPIO12, ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ,	
IO12	14	I/O	HS2_DATA2, SD_DATA2, EMAC_TXD3	
GND	15	Р	Ground	
IO13	16	I/O	GPIO13, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3, SD_DATA3, EMAC_RX_ER	
SHD/SD2*	17	I/O	GPIO9, SD_DATA2, SPIHD, HS1_DATA2, U1RXD	
SWP/SD3*	18	I/O	GPIO10, SD_DATA3, SPIWP, HS1_DATA3, U1TXD	
SCS/CMD*	19	I/O	GPIO11, SD_CMD, SPICS0, HS1_CMD, U1RTS	
SCK/CLK*	20	I/O	GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS	
SDO/SD0*	21	I/O	GPIO7, SD_DATA0, SPIQ, HS1_DATA0, U2RTS	
SDI/SD1*	22	1/0	GPIO8, SD_DATA1, SPID, HS1_DATA1, U2CTS	
			GPI015, ADC2_CH3, TOUCH3, MTDO, HSPICS0, RTC_GPI013,	
IO15 23 I/O HS2_CMD, SD_CMD, EMAC_RXD3				
			GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0,	
102	24	I/O	SD_DATA0	
100	GPIO0. ADC2 CH1. TOUCH1. BTC GPIO11.		GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1,	
100	25	I/O	EMAC_TX_CLK	
10.4	00		GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1,	
IO4	26	I/O	SD_DATA1, EMAC_TX_ER	
IO16	27	I/O	GPIO16, HS1_DATA4, U2RXD, EMAC_CLK_OUT	
1017	28	I/O	GPIO17, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180	
IO5	29	I/O	GPIO5, VSPICS0, HS1_DATA6, EMAC_RX_CLK	
IO18	30	I/O	GPIO18, VSPICLK, HS1_DATA7	
IO19	31	I/O	GPIO19, VSPIQ, UOCTS, EMAC_TXD0	
NC	32	-	-	
IO21	33	I/O	GPIO21, VSPIHD, EMAC_TX_EN	
RXD0	34	I/O	GPIO3, U0RXD, CLK_OUT2	
TXD0	35	I/O	GPIO1, U0TXD, CLK_OUT3, EMAC_RXD2	
IO22	36	I/O	GPIO22, VSPIWP, UORTS, EMAC_TXD1	
IO23	37	I/O	GPIO23, VSPID, HS1_STROBE	
GND	38	Р	Ground	

Note:

* Pins SCK/CLK, SDO/SD0, SDI/SD1, SHD/SD2, SWP/SD3 and SCS/CMD, namely, GPIO6 to GPIO11 are connected to the integrated SPI flash integrated on ESP32-SOLO-1 and are not recommended for other uses.

2.3 Strapping Pins

Please refer to ESP32-SOLO-1 schematics.

ESP32 has five strapping pins, which can be seen in Chapter 6 Schematics:

- MTDI
- GPIO0
- GPIO2
- MTDO
- GPI05

Software can read the value of these five bits from the register "GPIO_STRAPPING".

During the chip's system reset (power-on reset, RTC watchdog reset and brownout reset), the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down. The strapping bits configure the device boot mode, the operating voltage of VDD_SDIO and other system initial settings.

Each strapping pin is connected with its internal pull-up/pull-down during the chip reset. Consequently, if a strapping pin is unconnected or the connected external circuit is high-impendence, the internal weak pull-up/pull-down will determine the default input level of the strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or apply the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32.

After reset, the strapping pins work as the normal functions pins.

Refer to Table 4 for detailed boot modes' configuration by strapping pins.

Table 4: Strapping Pins

Voltage of Internal LDO (VDD_SDIO)							
Pin	Default	3.5	3V	1.8V			
MTDI	Pull-down	()	1			
			Booting Mode				
Pin	Default	SPI	Boot	Download Boot			
GPIO0	Pull-up	-	1	0			
GPIO2	Pull-down	Don't	-care	0			
	Debugging Log Printed on U0TXD During Booting?						
Pin	Default	UOTXD	Toggling	U0TXD Silent			
MTDO	Pull-up	-	1	0			
			Timing of SDIO Slave				
Pin	Default	Falling-edge Input	Falling-edge Input	Rising-edge Input	Rising-edge Input		
	Delault	Falling-edge Output	Rising-edge Output	Falling-edge Output	Rising-edge Output		
MTDO	Pull-up	0	0	1	1		
GPIO5	Pull-up	0	1	0	1		

Note:

Firmware can configure register bits to change the settings of "Voltage of Internal LDO (VDD_SDIO)" and "Timing of SDIO Slave" after booting.

3. Functional Description

This chapter describes the modules and functions integrated in ESP32-SOLO-1.

3.1 CPU and Internal Memory

ESP32-S0WD contains one low-power Xtensa[®] 32-bit LX6 microprocessor with the following features:

- 7-stage pipeline to support the clock frequency of up to 160 MHz
- 16/24-bit Instruction Set provides high code-density
- Support for Floating Point Unit
- Support for DSP instructions, such as 32-bit Multiplier, 32-bit Divider, and 40-bit MAC
- Support for 32 interrupt vectors from about 70 interrupt sources

The single-CPU interfaces include:

- Xtensa RAM/ROM Interface for instruction and data
- Xtensa Local Memory Interface for fast peripheral register access
- External and internal interrupt sources
- JTAG for debugging

3.1.1 Internal Memory

ESP32-SOWD's internal memory includes:

- 448 kB of ROM for booting and core functions.
- 520 kB (8 kB RTC FAST Memory included) of on-chip SRAM for data and instruction.
 - 8 kB of SRAM in RTC, which is called RTC FAST Memory and can be used for data storage; it is accessed by the main CPU during RTC Boot from the Deep-sleep mode.
- 8 kB of SRAM in RTC, which is called RTC SLOW Memory and can be accessed by the co-processor during the Deep-sleep mode.
- 1 kbit of eFuse, of which 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including Flash-Encryption and Chip-ID.

3.1.2 External Flash and SRAM

ESP32 supports up to four 16-MB external QSPI flash and SRAM with hardware encryption based on AES to protect developers' programs and data.

ESP32 can access the external QSPI flash and SRAM through high-speed caches.

- Up to 16 MB of external flash are memory-mapped onto the CPU code space, supporting 8-bit, 16-bit and 32-bit access. Code execution is supported.
- Up to 8 MB of external flash/SRAM memory are mapped onto the CPU data space, supporting 8-bit, 16-bit and 32-bit access. Data-read is supported on the flash and SRAM. Data-write is supported on the SRAM.

Note:

ESP32 chips with embedded flash do not support the address mapping between external flash and peripherals.

3.2 Crystal Oscillators

The ESP32 Wi-Fi/BT firmware can only support 40 MHz crystal oscillator for now.

3.3 RTC and Low-Power Management

With the use of advanced power management technologies, ESP32 can switch between different power modes (see Table 5).

- Power modes
 - Active mode: The chip radio is powered on. The chip can receive, transmit, or listen.
 - Modem-sleep mode: The CPU is operational and the clock is configurable. The Wi-Fi/Bluetooth baseband and radio are disabled.
 - Light-sleep mode: The CPU is paused. The RTC memory and RTC peripherals, as well as the ULP co-processor are running. Any wake-up events (MAC, host, RTC timer, or external interrupts) will wake up the chip.
 - Deep-sleep mode: Only the RTC memory and RTC peripherals are powered on. Wi-Fi and Bluetooth connection data are stored in the RTC memory. The ULP co-processor can work.
 - Hibernation mode: The internal 8-MHz oscillator and ULP co-processor are disabled. The RTC recovery
 memory is powered down. Only one RTC timer on the slow clock and some RTC GPIOs are active.
 The RTC timer or the RTC GPIOs can wake up the chip from the Hibernation mode.
- Sleep Patterns
 - Association sleep pattern: The power mode switches between the Active mode, Modem- and Lightsleep mode during this sleep pattern. The CPU, Wi-Fi, Bluetooth, and radio are woken up at predetermined intervals to keep Wi-Fi/BT connections alive.
 - ULP sensor-monitored pattern: The main CPU is in the Deep-sleep mode. The ULP co-processor takes sensor measurements and wakes up the main system, based on the data collected from sensors.

Power mode	Active	Modem-sleep	Light-sleep	Deep-sleep	Hibernation
Sleep pattern	Association sleep pattern			ULP sensor- monitored pattern	-
CPU	ON	ON	PAUSE	OFF	OFF
Wi-Fi/BT baseband and radio	ON	OFF	OFF	OFF	OFF
RTC memory and RTC pe- ripherals	ON	ON	ON	ON	OFF
ULP co-processor	ON	ON	ON	ON/OFF	OFF

Table 5: Functionalities Depending on the Power Modes

The power consumption varies with different power modes/sleep patterns and work statuses of functional modules. Please see Table 6 for details.

Power mode	Description	Power consumption	
	Wi-Fi Tx packet 14 dBm ~ 19.5 dBm		
Active (DE working)	Wi-Fi / BT Tx packet 0 dBm	Please refer to ESP32 Datasheet.	
Active (RF working)	Wi-Fi / BT Rx and listening		
	Association sleep pattern (by Light-sleep)	1 mA ~ 4 mA @DTIM3	
		Max speed 240 MHz: 30 mA ~ 50 mA	
Modem-sleep	The CPU is powered on.	Normal speed 80 MHz: 20 mA ~ 25 mA	
		Slow speed 2 MHz: 2 mA ~ 4 mA	
Light-sleep	-	0.8 mA	
	The ULP co-processor is powered on.	150 μA	
Deep-sleep	ULP sensor-monitored pattern	100 µA @1% duty	
	RTC timer + RTC memory	10 µA	
Hibernation	RTC timer only	5 µA	
Power off	CHIP_PU is set to low level, the chip is powered off	0.1 µA	

Note:

- When Wi-Fi is enabled, the chip switches between Active and Modem-sleep mode. Therefore, power consumption changes accordingly.
- In Modem-sleep mode, the CPU frequency changes automatically. The frequency depends on the CPU load and the peripherals used.
- During Deep-sleep, when the ULP co-processor is powered on, peripherals such as GPIO and I2C are able to work.
- When the system works in the ULP sensor-monitored pattern, the ULP co-processor works with the ULP sensor periodically; ADC works with a duty cycle of 1%, so the power consumption is 100 μA.

4. Peripherals and Sensors

4.1 Peripherals and Sensors Description

Table 7: Description of Peripherals and Sensors

Interface	Signal	Pin	Function
	ADC1_CH0	SENSOR_VP	
	ADC1_CH3	SENSOR_VN	
	ADC1_CH4	IO32	
	ADC1_CH5	IO33	
	ADC1_CH6	IO34	
	ADC1_CH7	IO35	
	ADC2_CH0	IO4	
ADC	ADC2_CH1	IOO	Two 12-bit SAR ADCs
	ADC2_CH2	IO2	
	ADC2_CH3	IO15	
	ADC2_CH4	IO13	
	ADC2_CH5	IO12	
	ADC2_CH6	IO14	
	ADC2_CH7	IO27	
	ADC2_CH8	IO25	
	ADC2_CH9	IO26	
Ultra-Low Noise	SENSOR_VP	IO36	Provides about 60 dB gain by using larger
Analog Pre-Amplifier	SENSOR_VN	IO39	capacitors on PCB
DAC	DAC_1	IO25	Two 8-bit DACs
	DAC_2	IO26	
	TOUCH0	IO4	
	TOUCH1	100	
	TOUCH2	IO2	
	TOUCH3	IO15	
Touch Sensor	TOUCH4	IO13	Capacitive touch sensors
	TOUCH5	IO12	
	TOUCH6	IO14	
	TOUCH7	IO27	
	TOUCH8	IO33	
	TOUCH9	IO32	
	HS2_CLK	MTMS	
	HS2_CMD	MTDO	
SD/SDIO/MMC Host	HS2_DATA0	IO2	Supports SD memory card V3.01 standard
Controller	HS2_DATA1	IO4	
	HS2_DATA2	MTDI	
	HS2_DATA3	MTCK	

Interface	Signal	Pin	Function
	PWM0_OUT0~2		
	PWM1_OUT_IN0~2		Three channels of 16 hit timera generate
	PWM0_FLT_IN0~2		Three channels of 16-bit timers generate PWM waveforms. Each channel has a pair
Motor PWM	PWM1_FLT_IN0~2	Any GPIOs*	of output signals, three fault detection
	PWM0_CAP_IN0~2		signals, three event-capture signals, and
	PWM1_CAP_IN0~2		three sync signals.
	PWM0_SYNC_IN0~2		
	PWM1_SYNC_IN0~2		
LED PWM	ledc_hs_sig_out0~7	Any GPIOs*	16 independent channels @80 MHz
	ledc_ls_sig_out0~7		clock/RTC CLK. Duty accuracy: 16 bits.
	U0RXD_in		
	U0CTS_in		
	U0DSR_in		
	U0TXD_out	Any GPIOs*	
	UORTS_out		
	U0DTR_out		
UART	U1RXD_in		Two UART devices with hardware
	U1CTS_in		flow-control and DMA
	U1TXD_out		
	U1RTS_out		
	U2RXD_in		
	U2CTS_in		
	U2TXD_out		
	U2RTS_out		
	I2CEXT0_SCL_in		
	I2CEXT0_SDA_in		
	I2CEXT1_SCL_in		
12C	I2CEXT1_SDA_in	Any GPIOs*	Two I2C devices in slave or master modes
	I2CEXT0_SCL_out		
	I2CEXT0_SDA_out		
	I2CEXT1_SCL_out		
	I2CEXT1_SDA_out		

Interface	Signal	Pin	Function				
	I2S0I_DATA_in0~15						
	I2S00_BCK_in						
	I2S00_WS_in						
	I2S0I_BCK_in	-					
	I2S0I_WS_in						
	I2S0I_H_SYNC						
	I2SOI_V_SYNC						
	I2S0I_H_ENABLE						
	I2S00_BCK_out						
	I2S0O_WS_out						
	I2S0I_BCK_out						
	I2SOI_WS_out		Stereo input and output from/to the audio				
I2S	I2SOO_DATA_out0~23	Any GPIOs*	codec, and parallel LCD data output				
	I2S1I_DATA_in0~15						
	I2S10_BCK_in						
	I2S10_WS_in						
	I2S1I_BCK_in						
	I2S1I_WS_in						
	I2S1I_H_SYNC						
	I2S1I_V_SYNC						
	I2S1I_H_ENABLE						
	I2S1O_BCK_out						
	I2S1O_WS_out						
	I2S1I_BCK_out						
	I2S1I_WS_out						
	I2S1O_DATA_out0~23						
Remote Controller	RMT_SIG_IN0~7	Any GPIOs*	Eight channels of IR transmitter and				
	RMT_SIG_OUT0~7		receiver for various waveforms				

Interface	Signal	Pin	Function
	SPIHD	SHD/SD2	
	SPIWP	SWP/SD3	
	SPICS0	SCS/CMD	
	SPICLK	SCK/CLK	
	SPIQ	SDO/SD0	
	SPID	SDI/SD1	
	HSPICLK	IO14	
	HSPICS0	IO15	Supports Standard SPI, Dual SPI, and
Parallel QSPI	HSPIQ	IO12	Quad SPI that can be connected to the
	HSPID	IO13	external flash and SRAM
	HSPIHD	IO4	
	HSPIWP	IO2	
	VSPICLK	IO18	
	VSPICS0	105	
	VSPIQ	IO19	
	VSPID	IO23	
	VSPIHD	IO21	
	VSPIWP	IO22	
	HSPIQ_in/_out		Standard SPI consists of clock,
	HSPID_in/_out		chip-select, MOSI and MISO. These SPIs
	HSPICLK_in/_out		can be connected to LCD and other
	HSPI_CS0_in/_out		external devices. They support the
	HSPI_CS1_out		following features:
General Purpose	HSPI_CS2_out	Any GPIOs*	 both master and slave modes;
SPI	VSPIQ_in/_out	,	• 4 sub-modes of the SPI format
	VSPID_in/_out		transfer that depend on the clock
	VSPICLK_in/_out		phase (CPHA) and clock polarity
	VSPI_CS0_in/_out		(CPOL) control;
	VSPI_CS1_out		• configurable SPI frequency;
	VSPI_CS2_out		• up to 64 bytes of FIFO and DMA.
	MTDI	IO12	
JTAG	MTCK	IO13	 JTAG for software debugging
UIAG	MTMS	IO14	
	MTDO	IO15	

Interface	Signal	Pin	Function
	SD_CLK	106	
	SD_CMD	IO11	SDIO interface that conforms to the
SDIO Slave	SD_DATA0	107	industry standard SDIO 2.0 card
ODIO Olave	SD_DATA1	IO8	specification.
	SD_DATA2	109	
	SD_DATA3	IO10	
	EMAC_TX_CLK	IOO	
	EMAC_RX_CLK	IO5	
	EMAC_TX_EN	IO21	
	EMAC_TXD0	IO19	
	EMAC_TXD1	IO22	
	EMAC_TXD2	IO14	
	EMAC_TXD3	IO12	
	EMAC_RX_ER	IO13	
	EMAC_RX_DV	1027	
	EMAC_RXD0	IO25	
EMAC	EMAC_RXD1	IO26	Ethernet MAC with MII/RMII interface
	EMAC_RXD2	TXD0	
	EMAC_RXD3	IO15	
	EMAC_CLK_OUT	IO16	
	EMAC_CLK_OUT_180	IO17	
	EMAC_TX_ER	IO4	
	EMAC_MDC_out	Any GPIOs*	
	EMAC_MDI_in	Any GPIOs*	
	EMAC_MDO_out	Any GPIOs*	
	EMAC_CRS_out	Any GPIOs*	
	EMAC_COL_out	Any GPIOs*	

Note:

• Functions of Motor PWM, LED PWM, UART, I2C, I2S, general purpose SPI and Remote Controller can be configured to any GPIO except GPIO6, GPIO7, GPIO8, GPIO9, GPIO10 and GPIO11.

• For the items marked with "Any GPIOs*" in the "Pin" column, users should note that GPIO6, GPIO7, GPIO8, GPIO9, GPIO10 and GPIO11 are connected to the integrated SPI flash of ESP32-SOLO-1 and are not recommended for other uses.

5. Electrical Characteristics

Note:

The specifications in this chapter have been tested under the following general condition: VDD = 3.3V, $T_A = 27^{\circ}$ C, unless otherwise specified.

5.1 Absolute Maximum Ratings

Parameter Symbol Min Тур Max Unit VDD 2.7 3.3 3.6 V Power supply Minimum current delivered by 0.5 А _ $|_{VDD}$ power supply -0.3 _ $0.25 \times V_{IO}^{1}$ V Input low voltage V_{IL} $0.75 \times V_{IO}^{1}$ $V_{IO}^{1}+0.3$ V Input high voltage V_{IH} _ Input leakage current $|_{IL}$ -_ 50 nΑ 2 рF Input pin capacitance C_{pad} _ -Output low voltage _ $0.1 \times V_{IO}^{1}$ V V_{OL} _ $0.8 \times V_{IO}^{1}$ V Output high voltage V_{OH} --Maximum output drive capability -_ 40 $|_{MAX}$ mΑ °C -40 _ 85 Storage temperature range T_{STR} °C Operating temperature range T_{OPR} -40 _ 85

Table 8: Absolute Maximum Ratings

1. V_{IO} is the power supply for a specific pad. More details can be found in the <u>ESP32 Datasheet</u>, Appendix IO_MUX. For example, the power supply for SD_CLK is the VDD_SDIO.

5.2 Wi-Fi Radio

Table 9: Wi-Fi Radio Characteristics

Description	Min	Typical	Max	Unit
Input frequency	2412	-	2484	MHz
Input reflection	-	-	-10	dB
	Tx power			
Output power of PA for 72.2 Mbps	13	14	15	dBm
Output power of PA for 11b mode	19.5	20	20.5	dBm
	Sensitivity	,		
DSSS, 1 Mbps	-	-98	-	dBm
CCK, 11 Mbps	-	-91	-	dBm
OFDM, 6 Mbps	-	-93	-	dBm
OFDM, 54 Mbps	-	-75	-	dBm
HT20, MCS0	-	-93	-	dBm
HT20, MCS7	-	-73	-	dBm

Description	Min	Typical	Max	Unit		
HT40, MCS0	-	-90	-	dBm		
HT40, MCS7	-	-70	-	dBm		
MCS32	-	-89	-	dBm		
Ad	Adjacent channel rejection					
OFDM, 6 Mbps	-	37	-	dB		
OFDM, 54 Mbps	-	21	-	dB		
HT20, MCS0	-	37	-	dB		
HT20, MCS7	-	20	-	dB		

5.3 BLE Radio

5.3.1 Receiver

Table 10: Receiver Characteristics - BLE

Parameter	Conditions	Min	Тур	Max	Unit
Sensitivity @30.8% PER	-	-	-97	-	dBm
Maximum received signal @30.8% PER	-	0	-	-	dBm
Co-channel C/I	-	-	+10	-	dB
	F = F0 + 1 MHz	-	-5	-	dB
	F = F0 - 1 MHz	-	-5	-	dB
	F = F0 + 2 MHz	-	-25	-	dB
Adjacent channel selectivity C/I	F = F0 - 2 MHz	-	-35	-	dB
	F = F0 + 3 MHz	-	-25	-	dB
	F = F0 - 3 MHz	-	-45	-	dB
	30 MHz ~ 2000 MHz	-10	-	-	dBm
Out of band blocking performance	2000 MHz ~ 2400 MHz	-27	-	-	dBm
Out-of-band blocking performance	2500 MHz ~ 3000 MHz	-27	-	-	dBm
	3000 MHz ~ 12.5 GHz	-10	-	-	dBm
Intermodulation	-	-36	-	-	dBm

5.3.2 Transmitter

Table 11: Transmitter Characteristic	s — BLE
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Parameter	Conditions	Min	Тур	Max	Unit
RF transmit power	-	-	0	-	dBm
Gain control step	-	-	±3	-	dBm
RF power control range	-	-12	-	+12	dBm

Parameter	Conditions	Min	Тур	Max	Unit
	F = F0 + 1 MHz	-	-14.6	-	dBm
	F = F0 - 1 MHz	-	-12.7	-	dBm
	F = F0 + 2 MHz	-	-44.3	-	dBm
Adjacent channel transmit power	F = F0 - 2 MHz	-	-38.7	-	dBm
	F = F0 + 3 MHz	-	-49.2	-	dBm
	F = F0 - 3 MHz	-	-44.7	-	dBm
	F = F0 + > 3 MHz	-	-50	-	dBm
	F = F0 - 3 MHz	-	-50	-	dBm
$\Delta f1_{avg}$	-	-	-	265	kHz
$\Delta f_{2\max}$	-	247	-	-	kHz
$\Delta f_{2avg}/\Delta f_{1avg}$	-	-	-0.92	-	-
ICFT	-	-	-10	-	kHz
Drift rate	-	-	0.7	-	kHz/50 μs
Drift	-	-	2	-	kHz

5.4 Reflow Profile

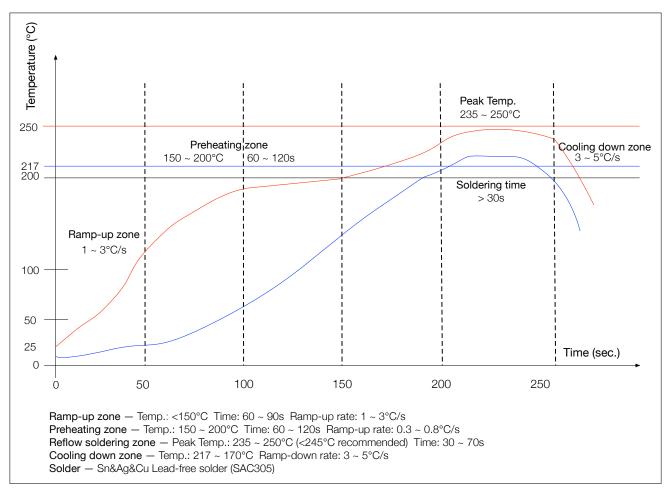
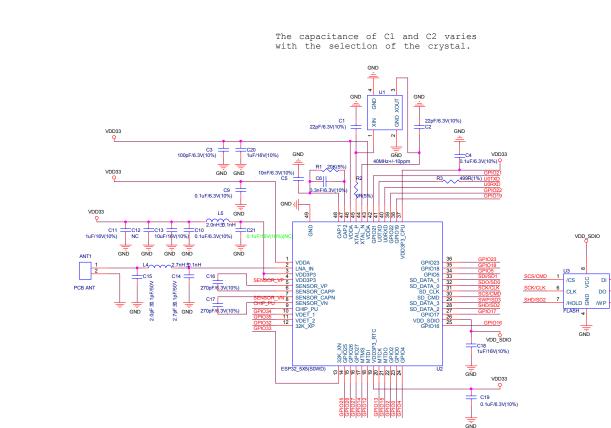


Figure 2: Reflow Profile

6. Schematics



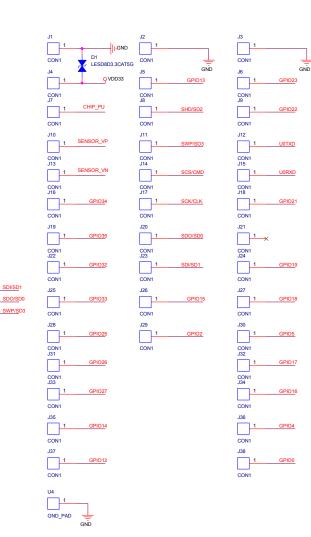


Figure 3: ESP32-SOLO-1 Schematics

7. Peripheral Schematics

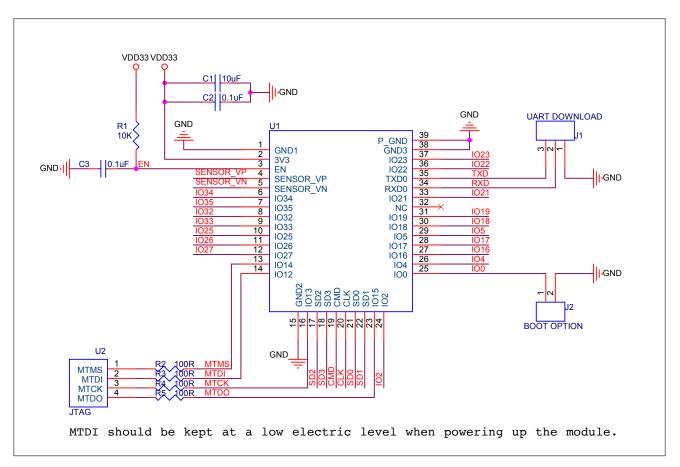
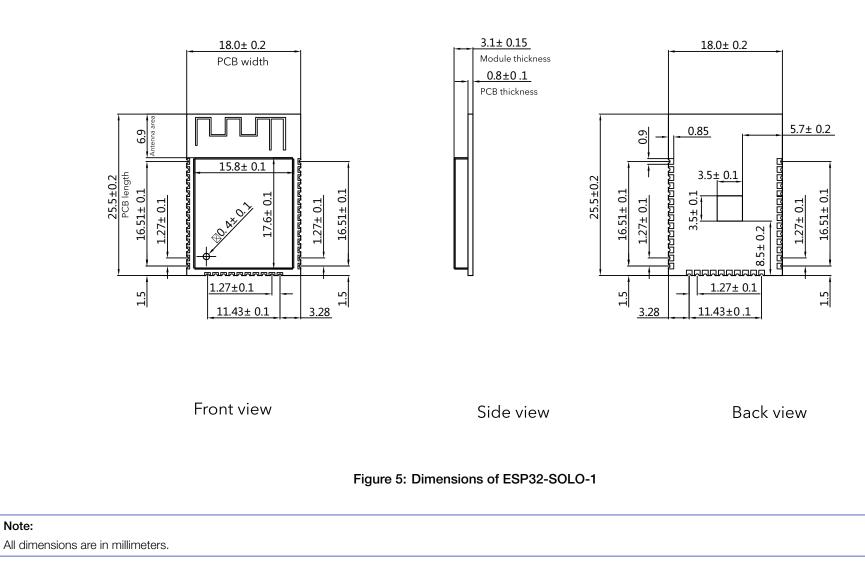


Figure 4: ESP32-SOLO-1 Peripheral Schematics

Note:

- Soldering Pad 39 to the Ground of the base board is not necessary for a satisfactory thermal performance. If users do want to solder it, they need to ensure that the correct quantity of soldering paste is applied.
- When ESP32 is powered on and off repeatedly by switching the power rails, and there is a large capacitor on the VDD33 rail, a discharge circuit can be added to the VDD33 rail. Please find details in Chapter **Peripheral Schematics**, in ESP-WROOM-32 Datasheet.

Dimensions 8.



ESP32-SOLO-1 Datasheet V1.0

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DIMENSIONS

9. Learning Resources

9.1 Must-Read Documents

The following link provides documents related to ESP32.

ESP32 Datasheet

This document provides an introduction to the specifications of the ESP32 hardware, including overview, pin definitions, functional description, peripheral interface, electrical characteristics, etc.

- ESP32 Technical Reference Manual The manual provides detailed information on how to use the ESP32 memory and peripherals.
- ESP32 Hardware Resources

The zip files include the schematics, PCB layout, Gerber and BOM list of ESP32 modules and development boards.

• ESP32 Hardware Design Guidelines

The guidelines outline recommended design practices when developing standalone or add-on systems based on the ESP32 series of products, including ESP32, the ESP-WROOM-32 module, and ESP32-DevKitC—the development board.

ESP32 AT Instruction Set and Examples

This document introduces the ESP32 AT commands, explains how to use them, and provides examples of several common AT commands.

9.2 Must-Have Resources

Here are the ESP32-related must-have resources.

• ESP32 BBS

This is an Engineer-to-Engineer (E2E) Community for ESP32 where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

• ESP32 GitHub

ESP32 development projects are freely distributed under Espressif's MIT license on GitHub. It is established to help developers get started with ESP32 and foster innovation and the growth of general knowledge about the hardware and software surrounding ESP32 devices.

ESP32 Tools

This is a webpage where users can download ESP32 Flash Download Tools and the zip file "ESP32 Certification and Test".

• ESP-IDF

This webpage links users to the official IoT development framework for ESP32.

ESP32 Resources

This webpage provides the links to all available ESP32 documents, SDK and tools.